

Session 2 – Ecological field methods.

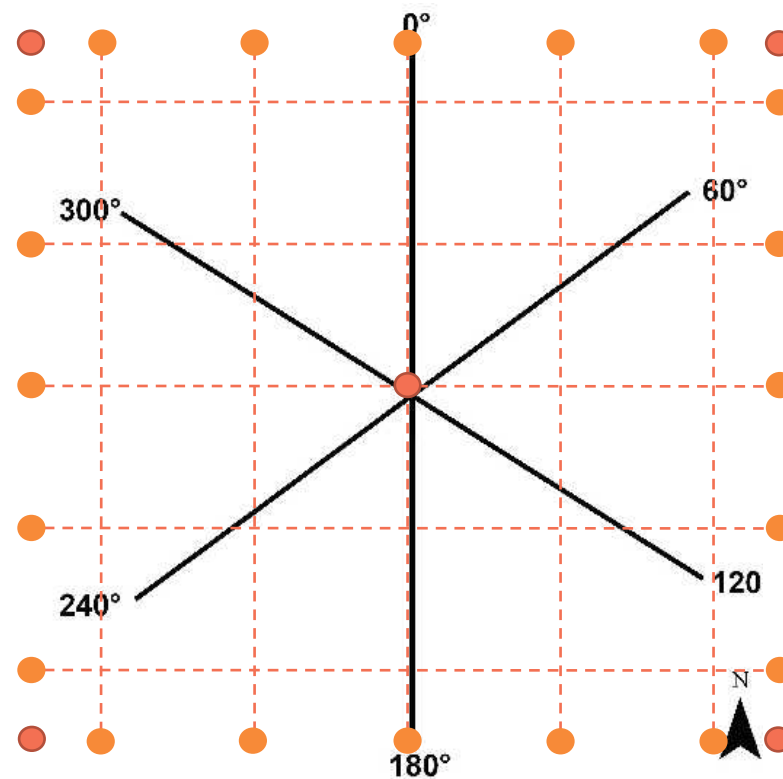
11 – 12:30





Fractional Cover

SLATS/Landcover Integration



TERN is supported by the Australian Government through the National Collaborative Research Infrastructure Strategy and the Super Science Initiative.

The use of AusPlots data for remote sensing validation

Method designed to provide RS compatible data

Data from 1000 point intercepts can be easily be converted to compatible form.

Well defined, homogeneous 1ha square that is aligned to the grid assists with validation activities.

Field data can be used to determine vegetation mapping communities, and the plot areas used for supervised classification techniques.

LAI information fed back to AusCover to validate their RS products.

Comparison with the SLATS star Transects

Collected for different **purposes**

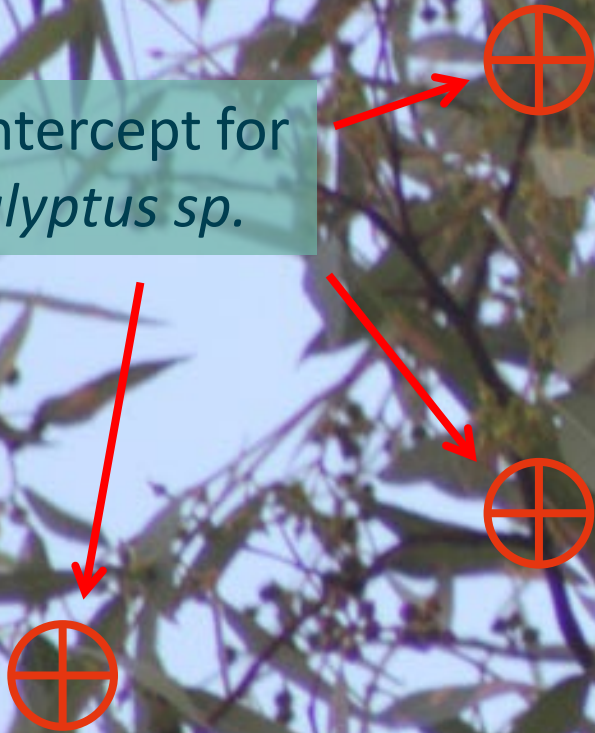
SLATS

- For RS validation of land cover products
- Slats method is well refined for that purpose

AusPlots

- To provide data to inform a wide range of ecological research ***along with*** providing data for a wide range of remote sensing purposes.
- AusPlots well designed for maximum widespread utility of data.
- Can be summarised into SLATS form.

An intercept for *Eucalyptus* sp.



“In Canopy Sky” for *Eucalyptus* sp.





Species ID

- + Inventory species occurring in the plot
 - + Collect voucher specimens (enhanced protocol)
 - + Give all specimens a 'field name'
 - + Field names carry over to other protocols (e.g. Cover)
 - + Herbarium or EMSA-approved botanist to verify species names for all voucher specimens

These EMSA protocols are ideal for species ID.....

But if you intend to do spectral work on the samples the process would generally be to set up the spectrometer in a "Field Lab" then....

Once the barcode is attached then place the sample in a large snap lock bag with some damp paper towel (Wet and wrung out again) and place in a camp fridge in the vehicle.

Plant spectra are most susceptible to changes in moisture level.





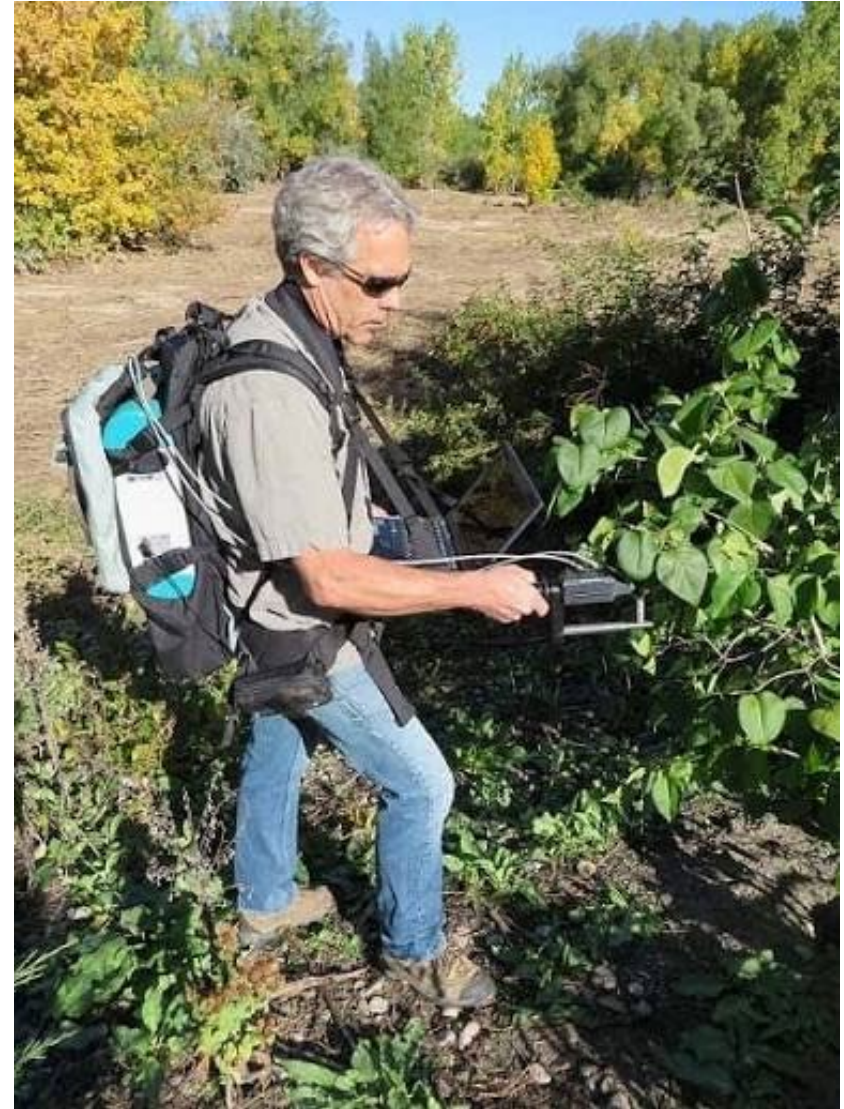
Basal Area Module

- + Requires Floristics vouchers
 - + Measures the average area within the plot occupied by trees
 - + Provides information on stand density.
 - + **DBH Protocol**
 - + Plot sampling
 - + Measure DBH for all trees within 40 x 40 m or 100 x 100 m area
 - + **Basal Wedge Protocol**
 - + Point sampling, rapid assessment
 - + Using handheld gauge (basal wedge)
- + Basal area data uses:
 - + To monitor tree growth
 - + To calculate tree biomass and carbon sequestration (using allometric equations)



Unmixing

- Cover per species (From point intercept)
- Or individual species spectra
- (Usually averaged across 10 or more readings)





Method

Using the LAI



TERN is supported by the Australian Government through the National Collaborative Research Infrastructure Strategy and the Super Science Initiative.

LAI Measurements

- AusCover desire to validate LAI and FPC products
- FPC validated by point intercept
- LAI can be validated by Hemispherical Photography or LAI2200
- Hemispherical Photography
 - Potentially more accurate
 - Harder to set up in the field
 - Lowest height about 40-50 cm above ground level
 - Harder to process in the office – More work
 - Harder to get high number of samples
 - Larger volume of data

- LAI 2200
 - Operates closer to the ground – more appropriate for Rangelands
 - Easy to take a high number of samples
 - Instant processing – No work later
 - Easy to use for non experts to use in the field
 - Much quicker to use

LAI 2200 Seen as best outcome considering the needs of both AusCover (Data) and AusPlots (Speed and ease of use)

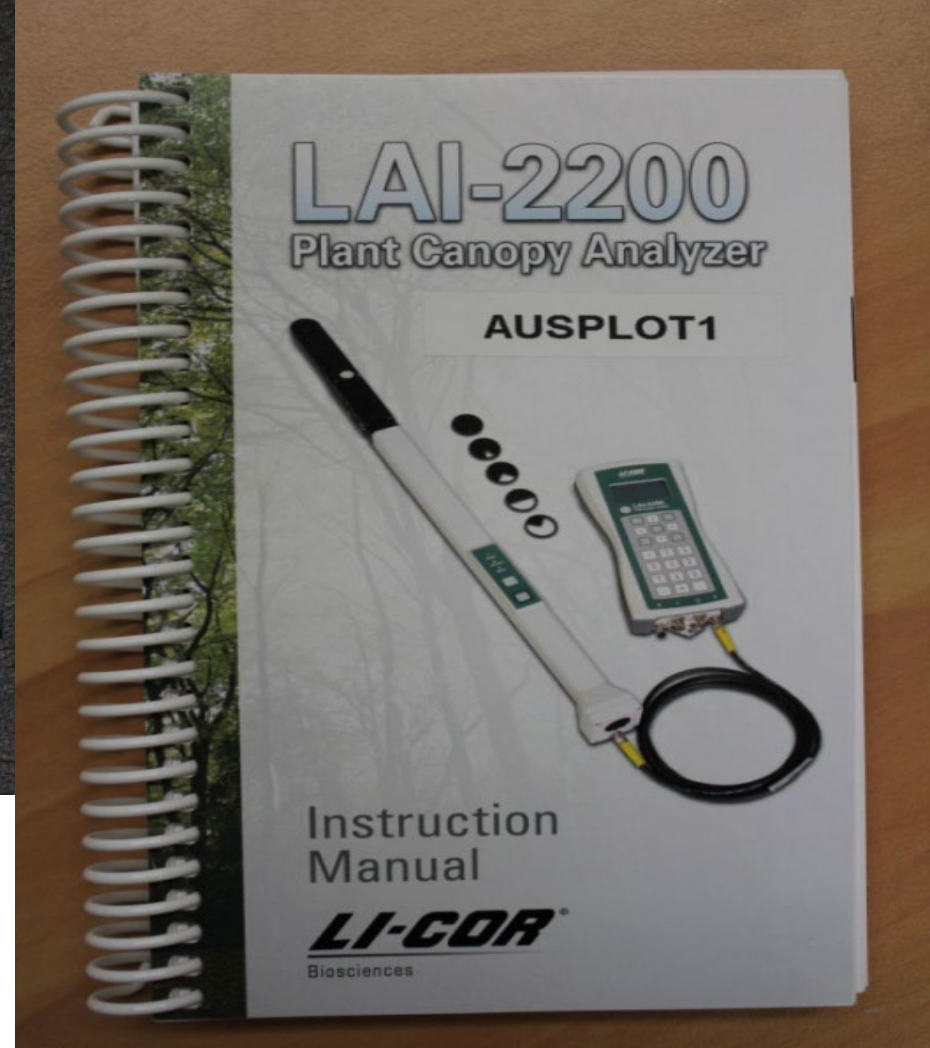
LAI 2200

- Need to avoid direct sunlight
 - Diffuse light
 - Constant cloud
 - Dawn or dusk
- Need above/ clear sky reference fairly regularly (issue in really high canopy areas)
- Recent field trip collected data to inform of optimal sampling strategy.
- Not Operationally useful for chenopods
 - (re: number of samples)

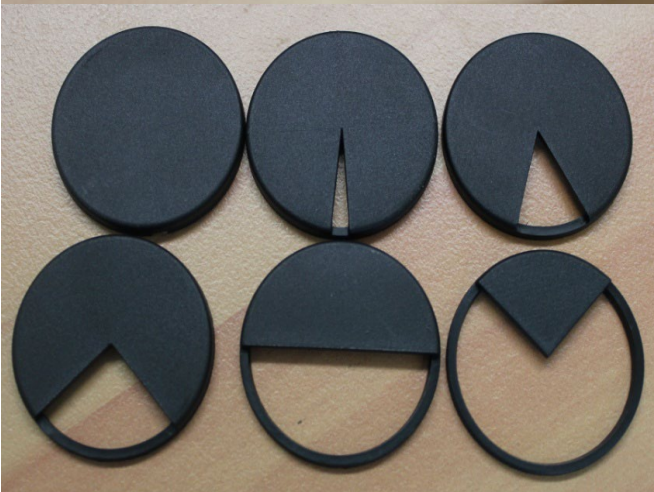


The device will come pre- set up – There will be no need to connect the “wand” to the Console. You will only need to use the “wand”.

Remove it from the Pelican case. The manual will be in the case but we ask that you follow the AusPlots manual in the first instance, and then attempt calling AusPlots staff before you use the manual or change any settings. The device is significantly more complex than our application.



We have simplified its operation to make it easier to use in the field.



The Sensor head and fitting the lens cover



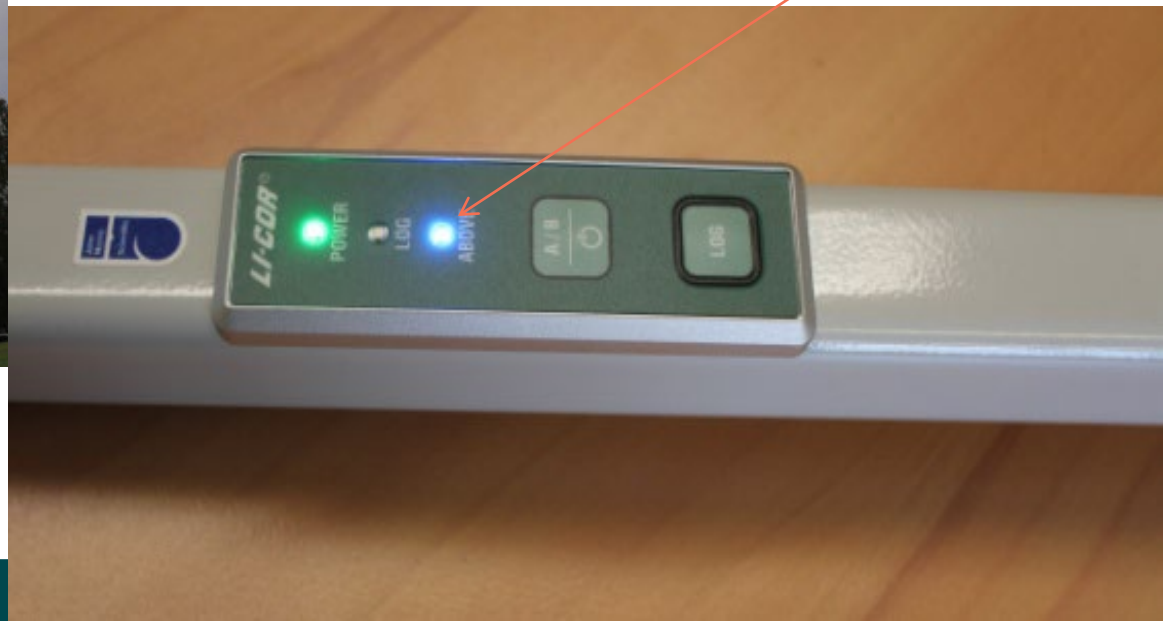
Before



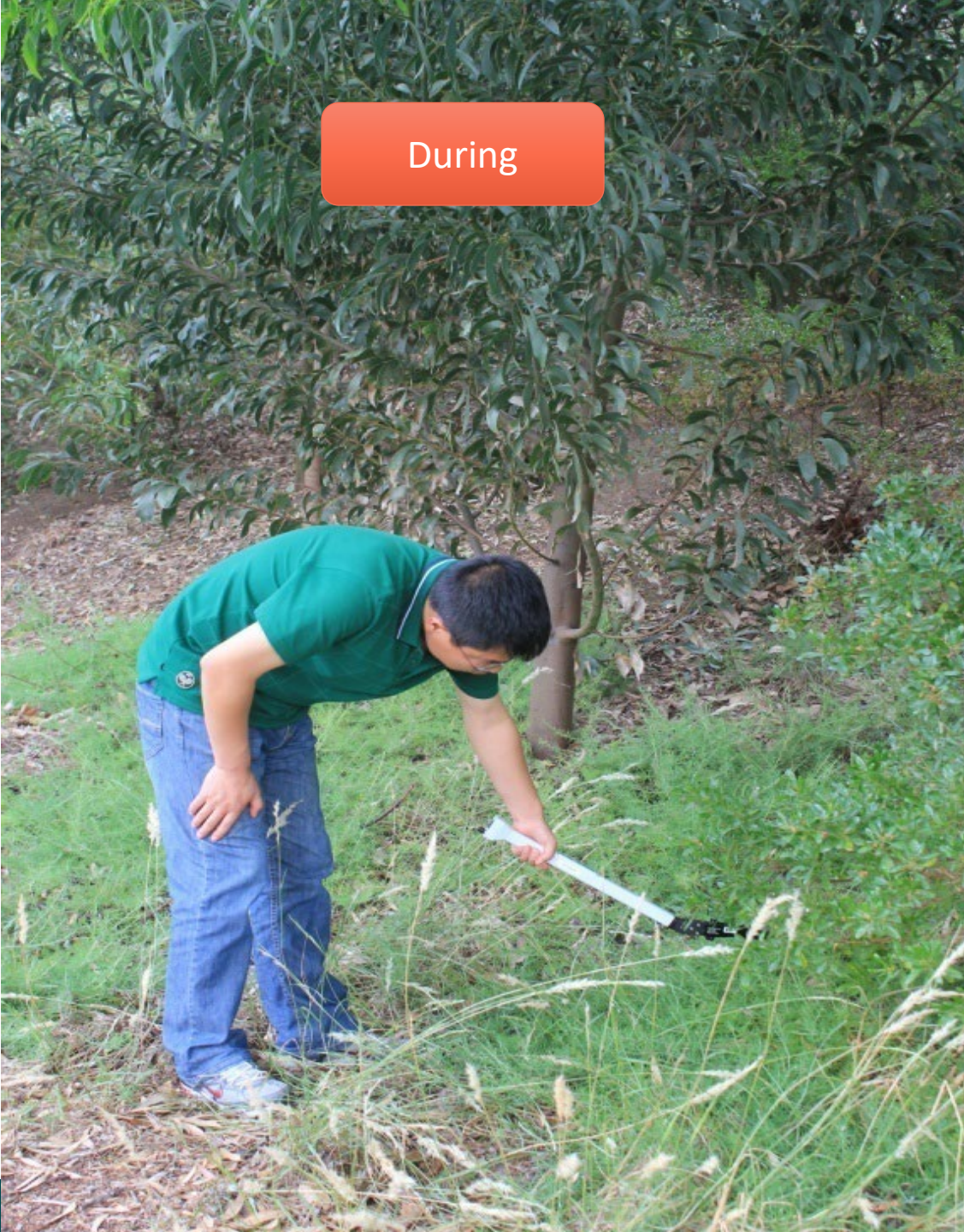
Taking an “above” Reference
– Note the overcast sky



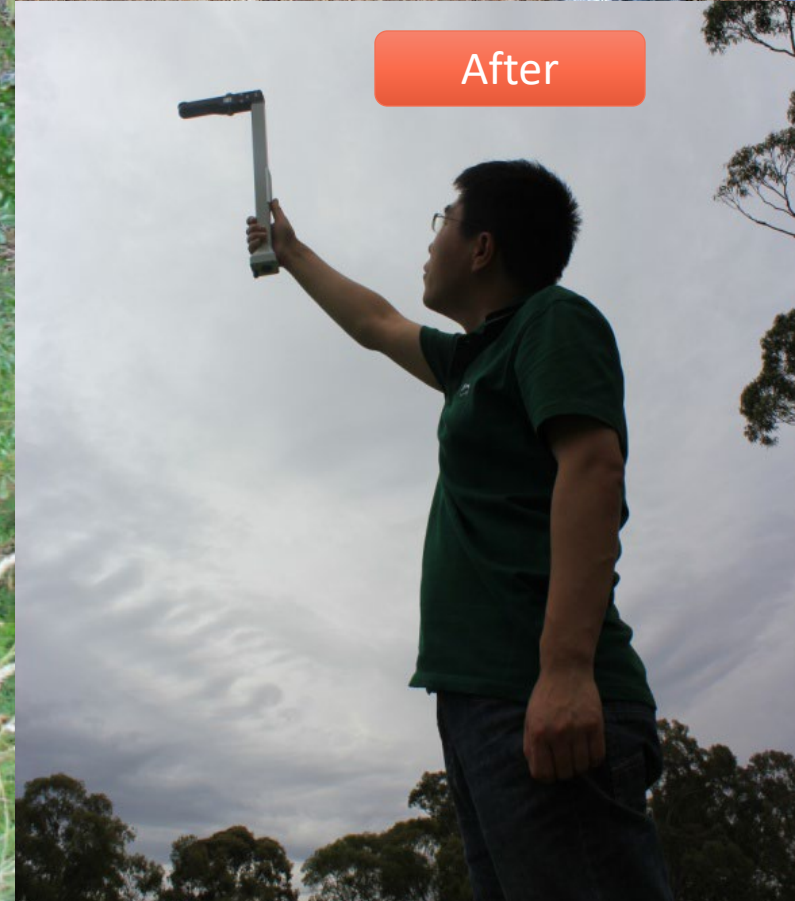
The wand set up for logging points and an above reference



During

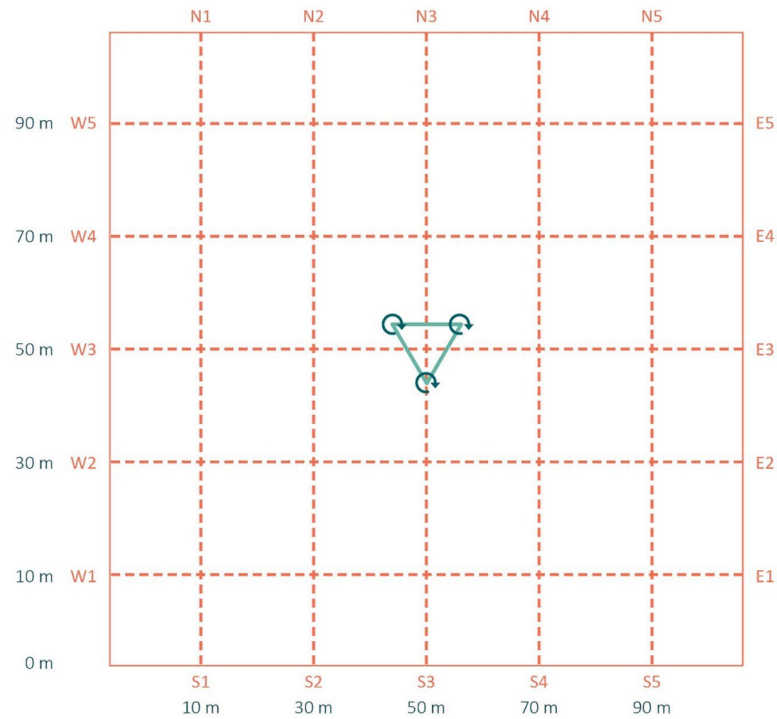


After

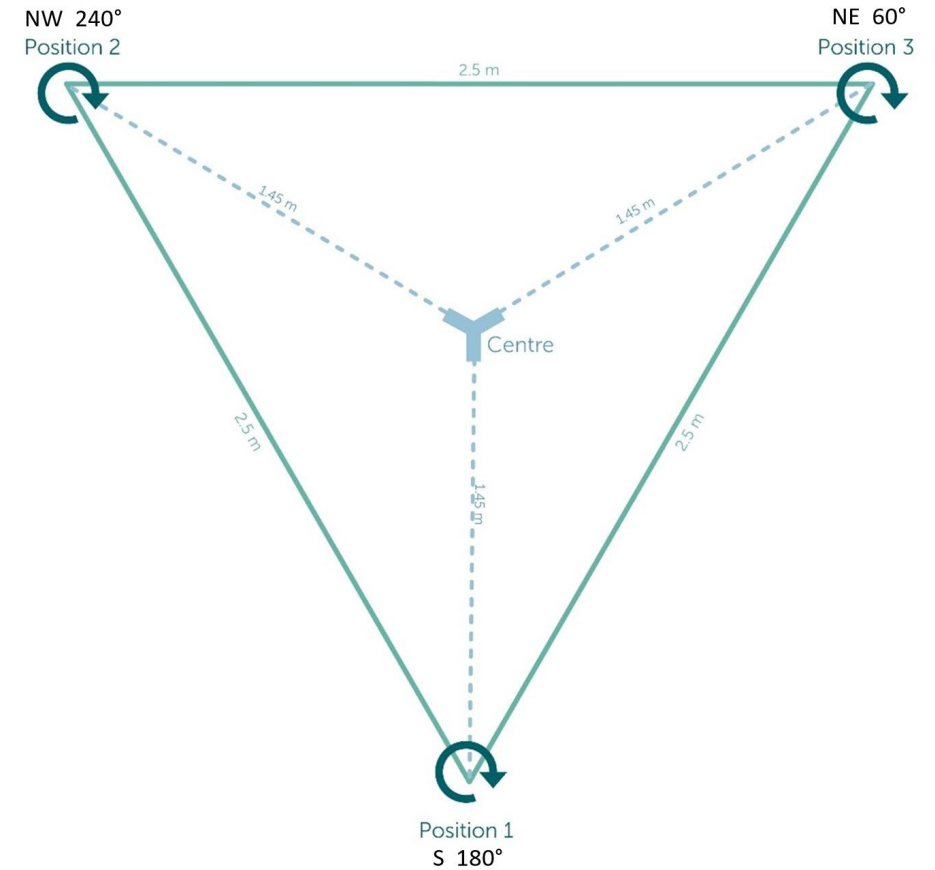




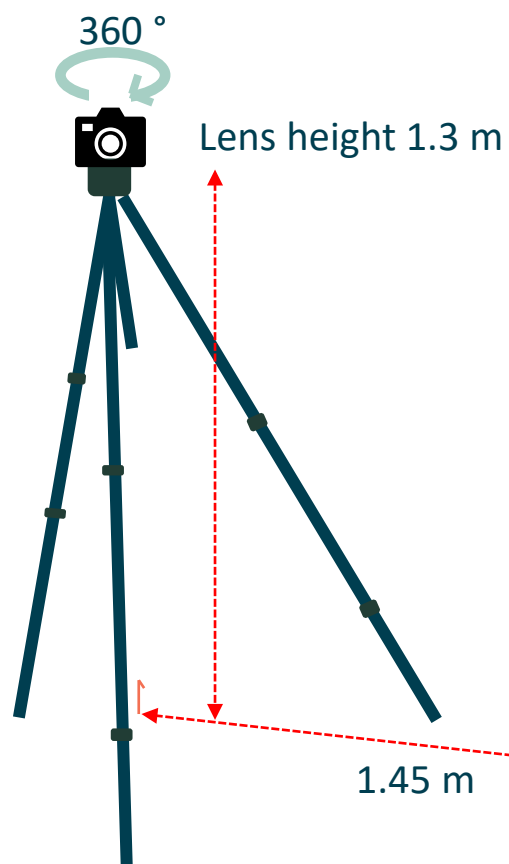
Photopoints Module



- Photopoint position (indicative location/orientation)
- Photopoint (indicative location)
- Point-intercept transect
- Core plot



**Panorama
Position 1**
south



permanent photopoint marker
(star dropper)

tape mark at 1.3 m

tape mark at 1.05 m

**Panorama
Position 2**
north-west

1.45 m

1.45 m

**Panorama
Position 3**
north-east



NE

NW



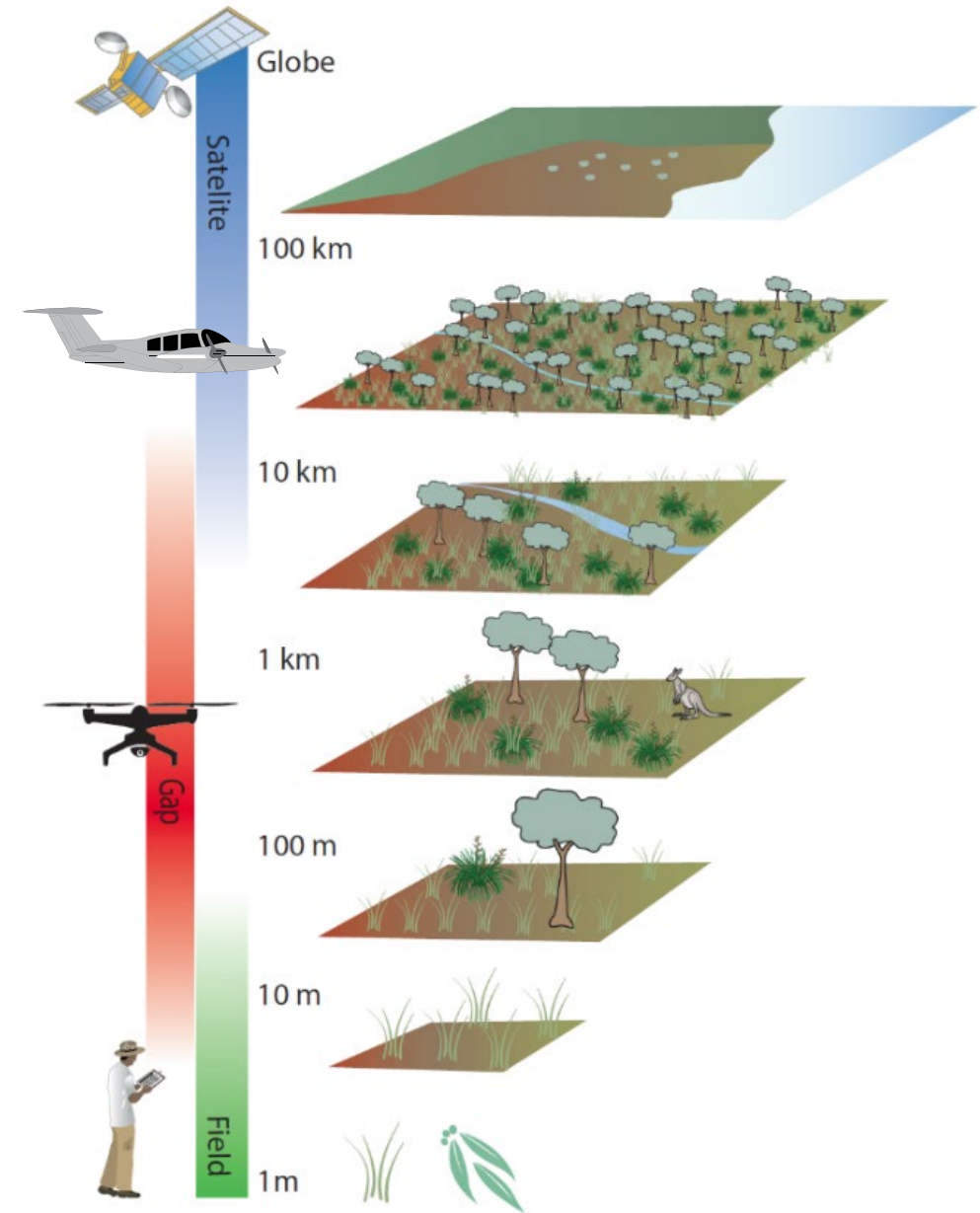
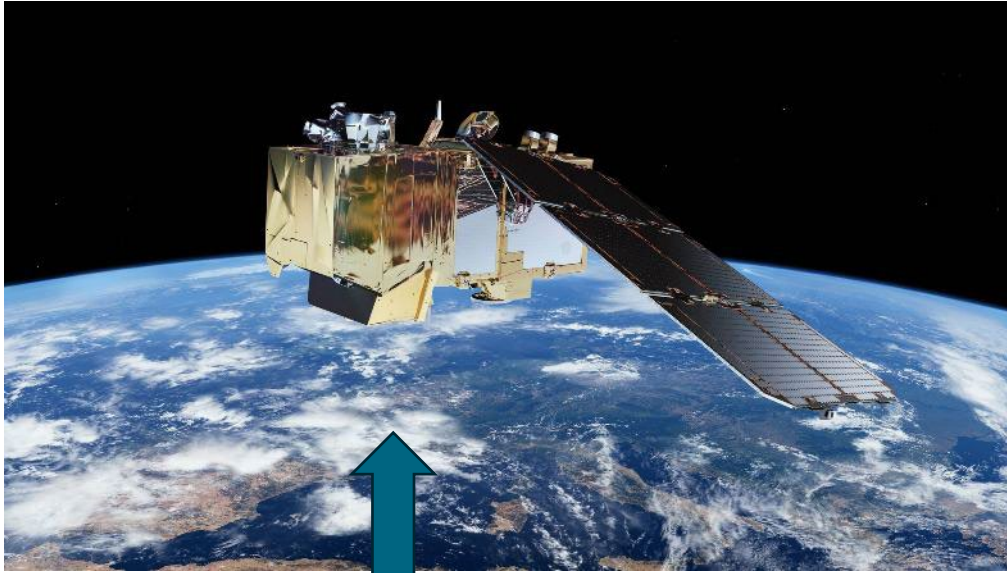
tern DroneScape

Operationalising drone remote sensing for ecosystem assessment in Australia

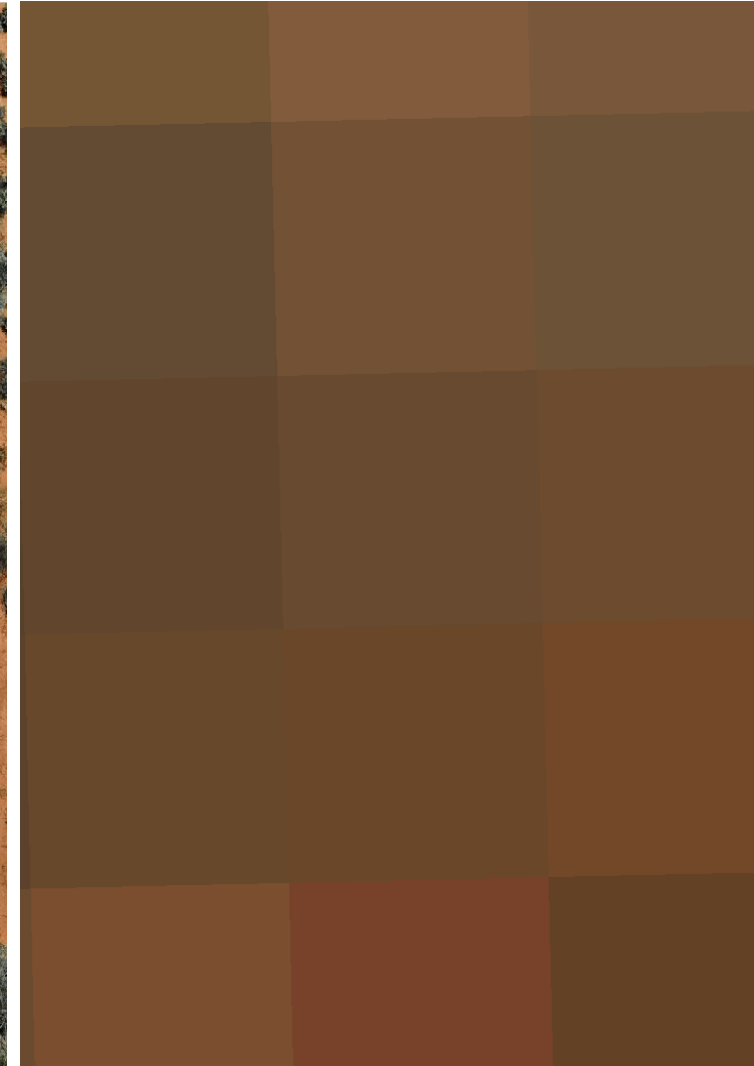
Arko Lucieer, Ben Sparrow, Juan Carlos (JC) Montes Herrera,
Carla Franson, Troy Bektas, Gigi Lynn

Acknowledgements: Poornima Sivanandam, Krishna Lamsal, Alice Robbins,
Ryan Haynes, James Gregory, Chris Callaghan, Caitlyn Smart, Darren Turner

Why DroneScape?



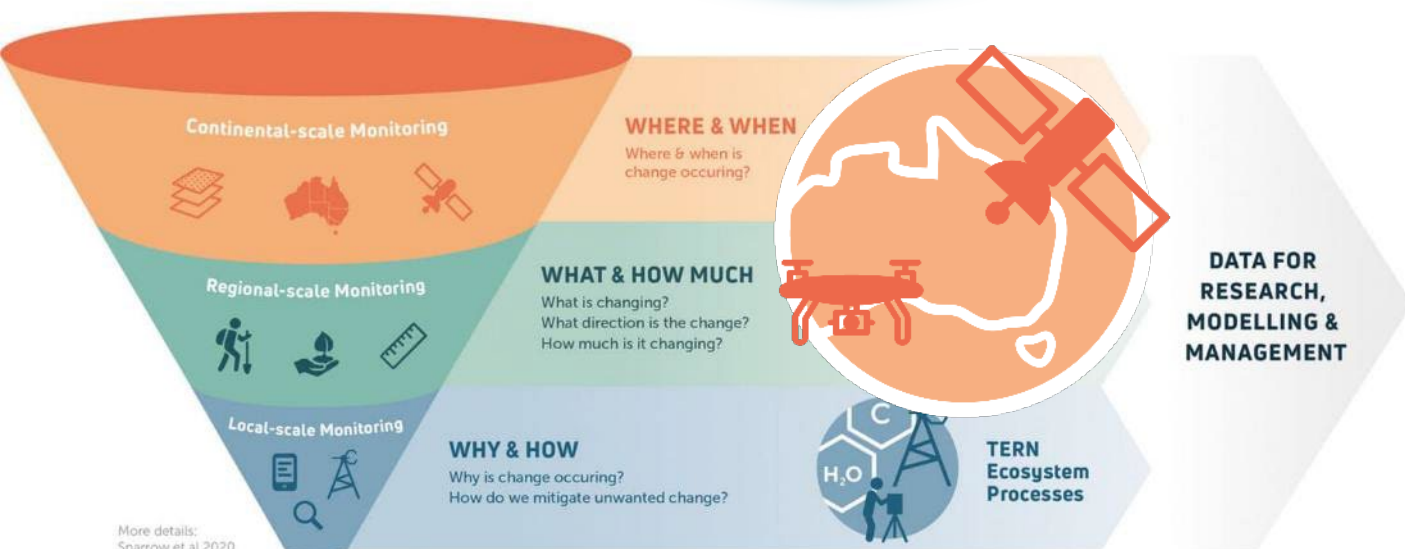
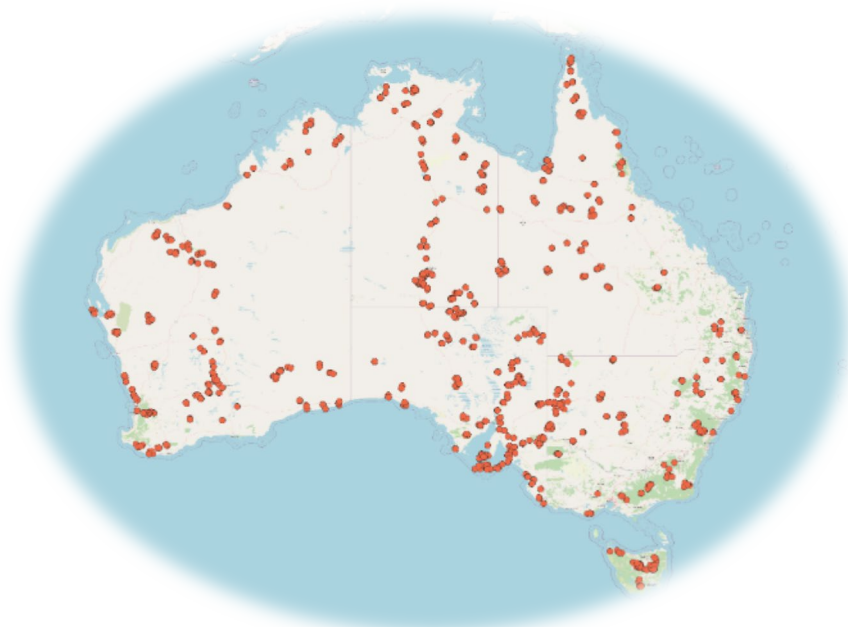
Drones for ecological monitoring





tern DroneScape

Ecosystem Research Infrastructure



More details:
Sparrow et al 2020





DJI Matrice 350 RTK

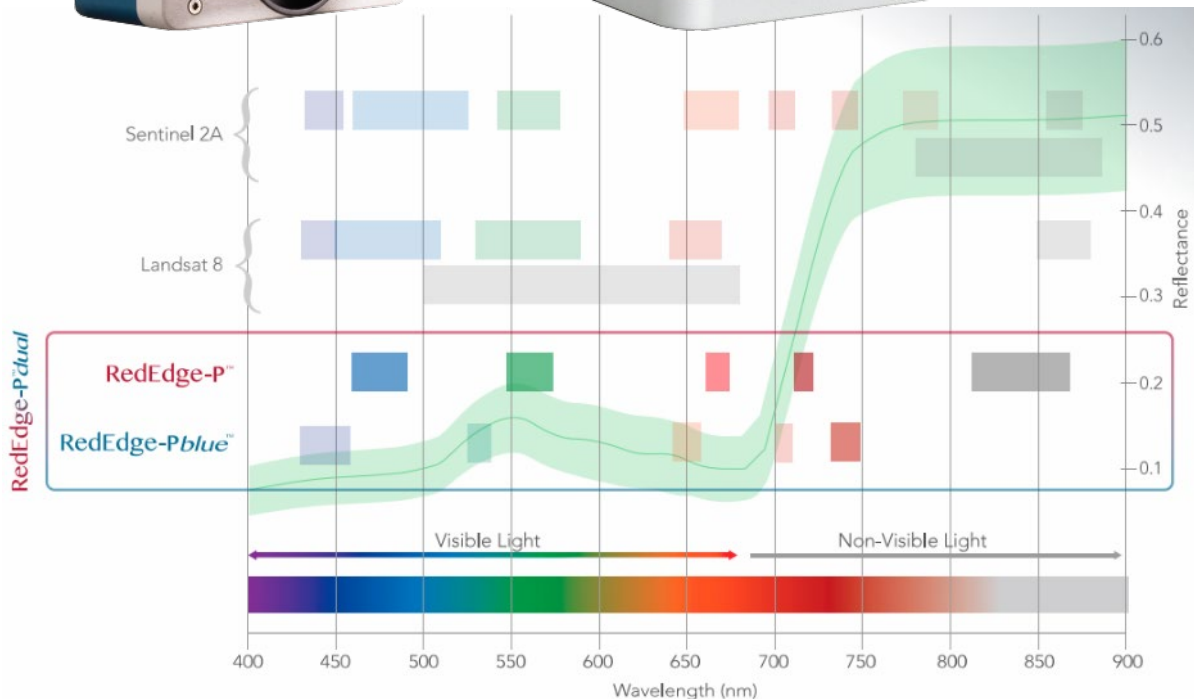
- 35 min flight time covering 350 x 350 m = 12 ha centred around a 1 ha field plot
- Dual frequency RTK GNSS: ~5 cm accuracy
- Multi-sensor payload capacity
- Resolution: 1 cm RGB and 5 cm multispec flying at @ 80 m AGL



Micasense Rededge-P Dual 10-band multispectral



- 10 spectral bands in VNIR
- ~5 cm pixel size @ 80 m flying height
- Incident light sensor
- Reflectance panel

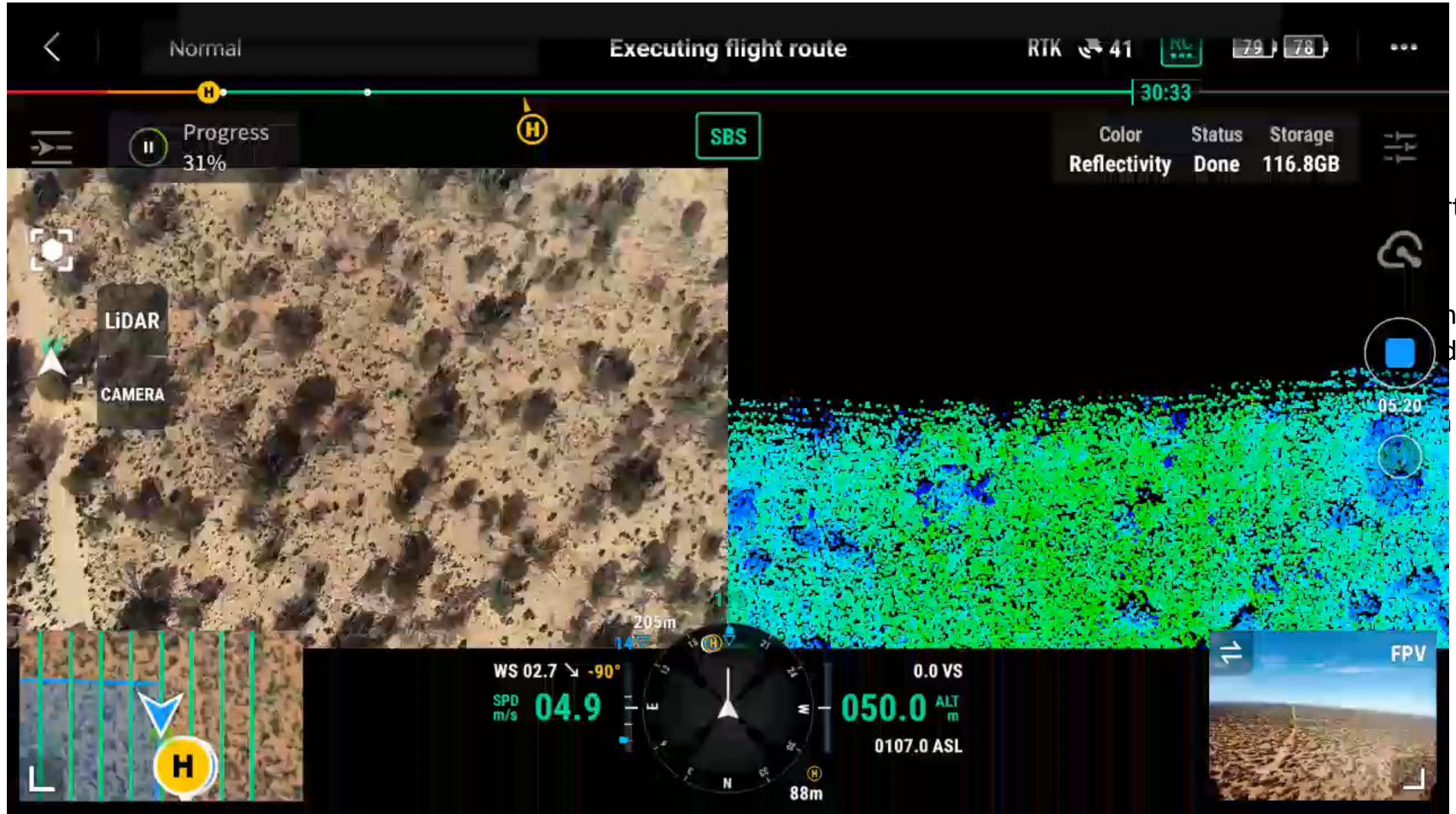


DJI Zenmuse P1 full-frame RGB



- 45 megapixel full-frame RGB camera
- RTK GNSS geotagged
- ~1 cm pixel size @ 80 m flying height

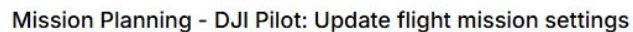
DJI Zenmuse L2 lidar





 Search

Steps Guidelines Warnings References Troubleshooting Metadata Materials Metrics Acknowledgements



FLIGHT ALTITUDE

Target Surface to Takeoff Point 0

Canopy > 10 m

Sat Target Surface to Takeoff Point value?

Canopy < 10 m

Target Surface to Takeoff Point height of canopy

50 m

20 m

10 m

10 m

TAKE OFF POINT

TAKE OFF POINT

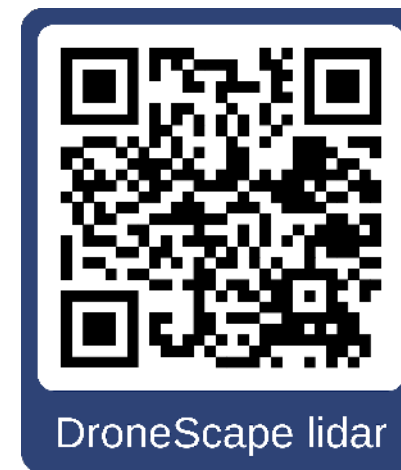
Source: Authors (2022)

Figures are provided from the University of Melbourne Centre for Environmental Science and Survey authors: Daria Trach, Thomas Goudier, Robert J. Brown, and Lucy R. Brown. Figures are provided from the University of Melbourne Centre for Environmental Science and Survey authors: Daria Trach, Thomas Goudier, Robert J. Brown, and Lucy R. Brown. Figures are provided from the University of Melbourne Centre for Environmental Science and Survey authors: Daria Trach, Thomas Goudier, Robert J. Brown, and Lucy R. Brown.

7 After updating the mission settings, the general and advanced settings should be as below.



DroneScape imagery

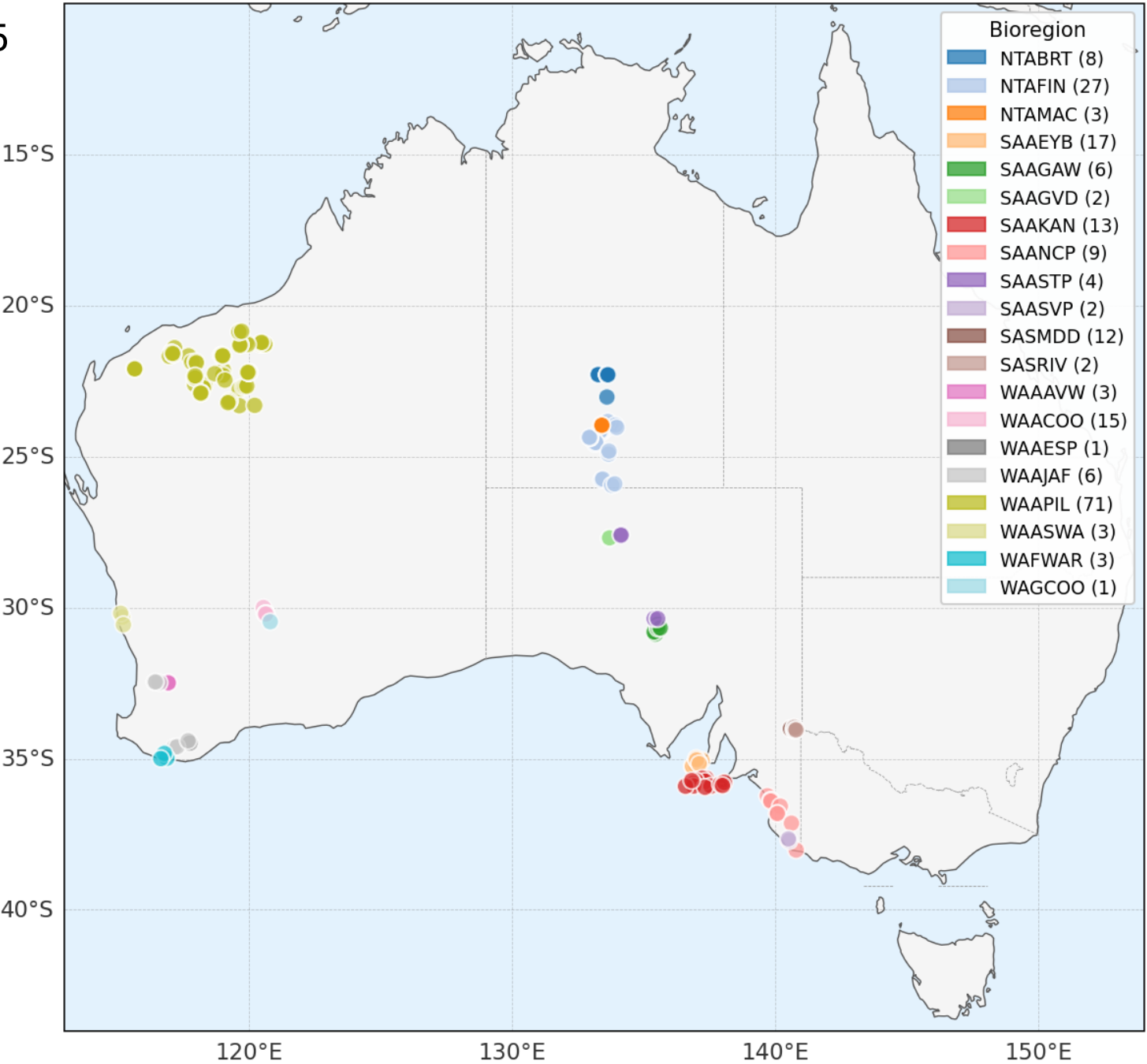


DroneScape lidar



NatureScan

October 2025



208 of ~ 1000
TERN plots 🧡

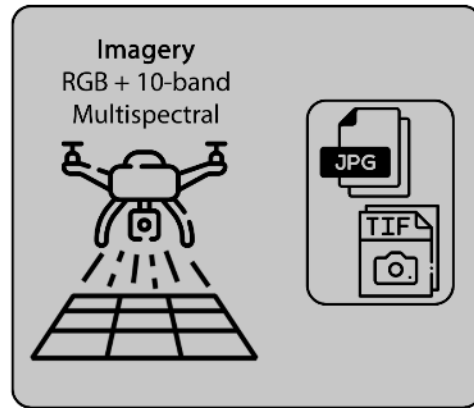






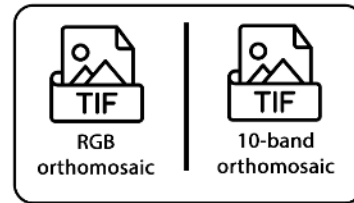


Data collection → Pre-processing → Processing → Outputs

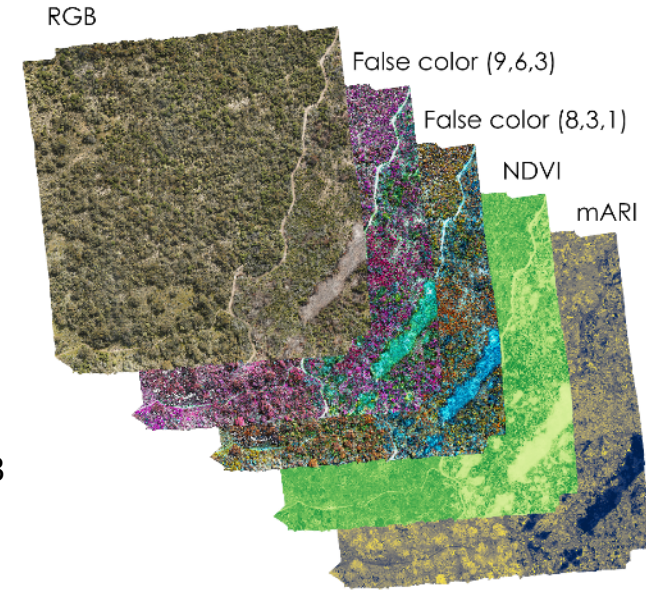


Agisoft
Metashape

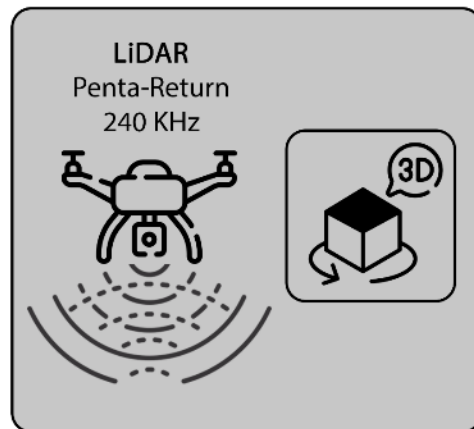
The Agisoft Metashape logo is shown next to a small icon of a Python file with a .PY extension.



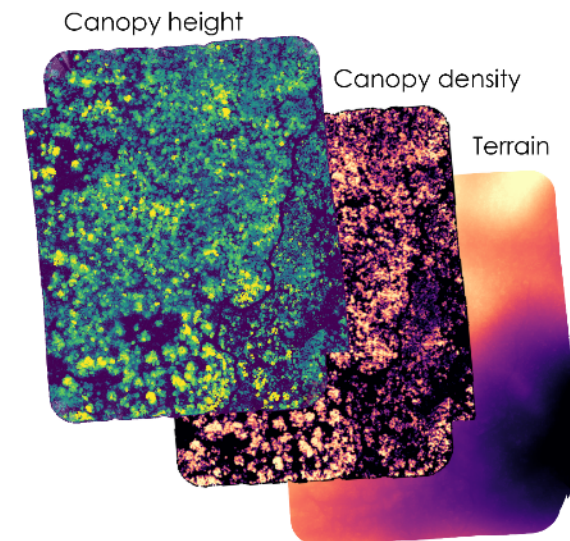
Montero et al. 2023

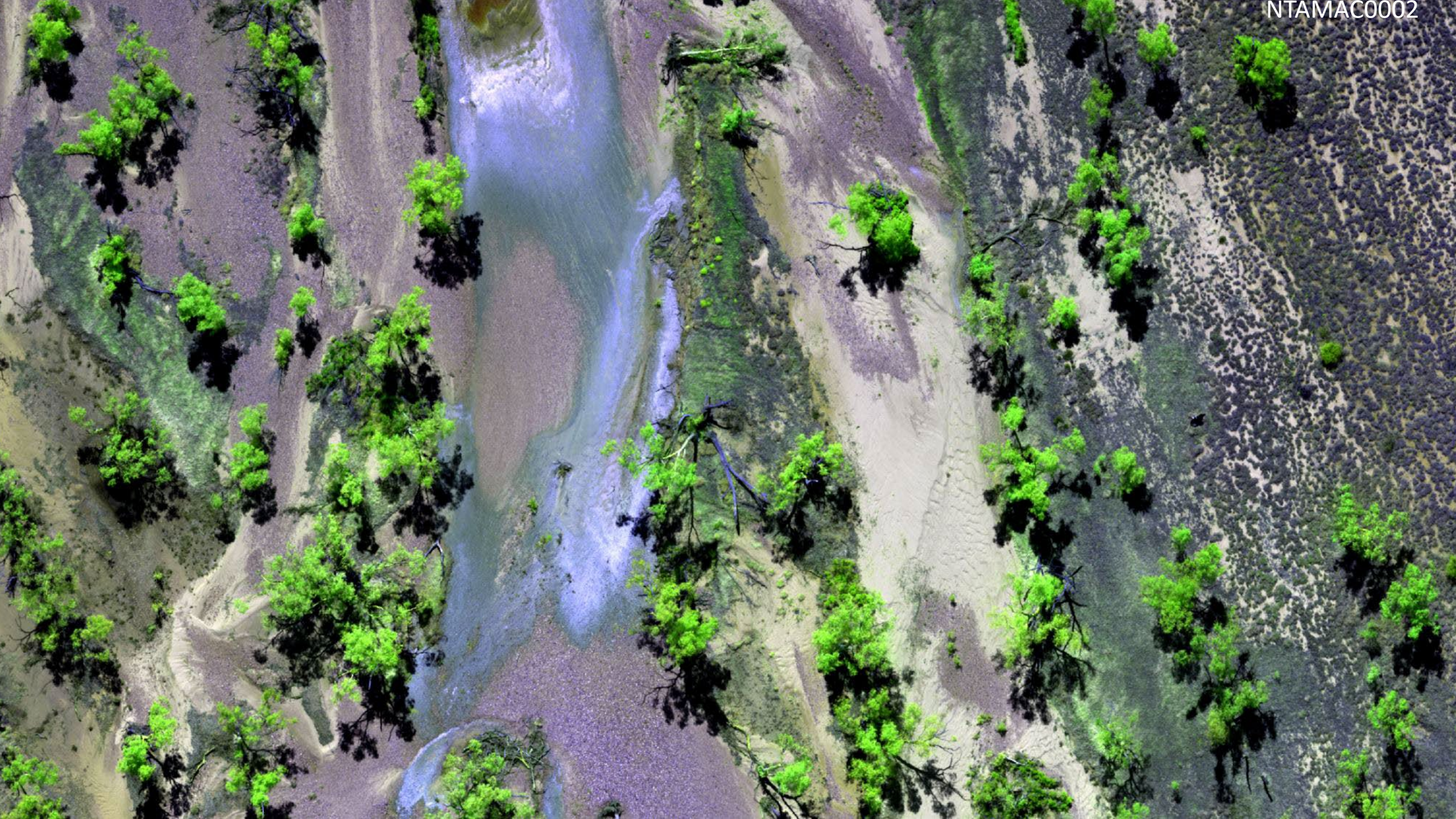


Data collection → Pre-processing → Processing → Outputs



Roussel et al. 2020







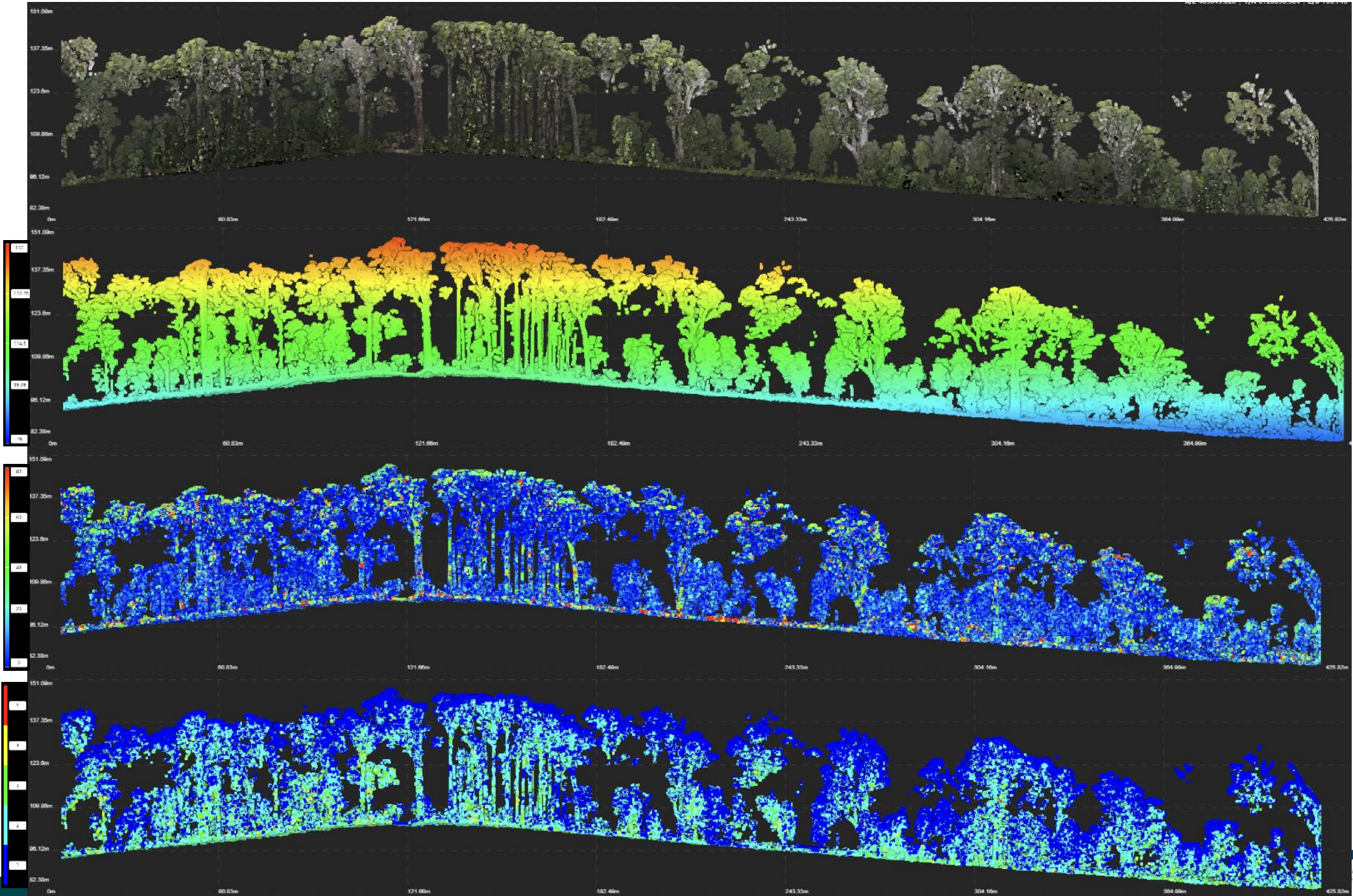
WAFWAR0003

RGB point cloud

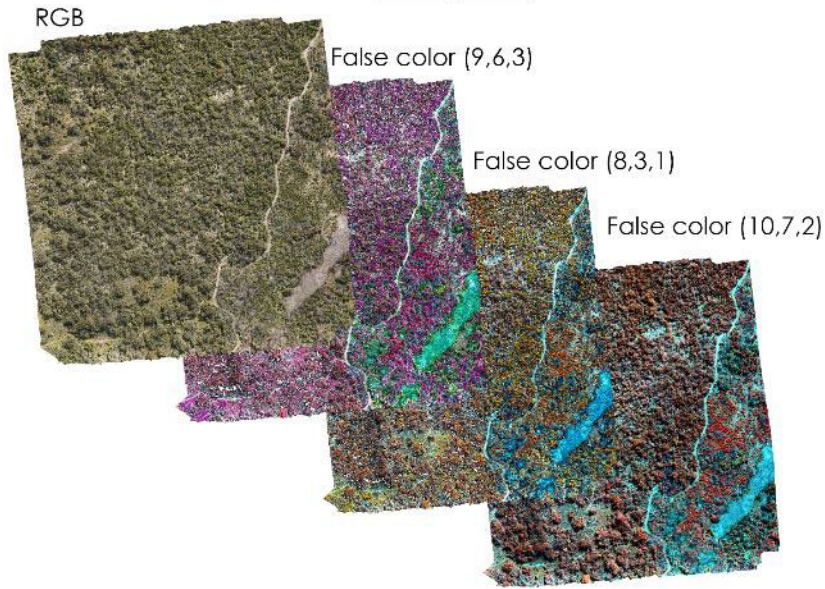
Height

Intensity

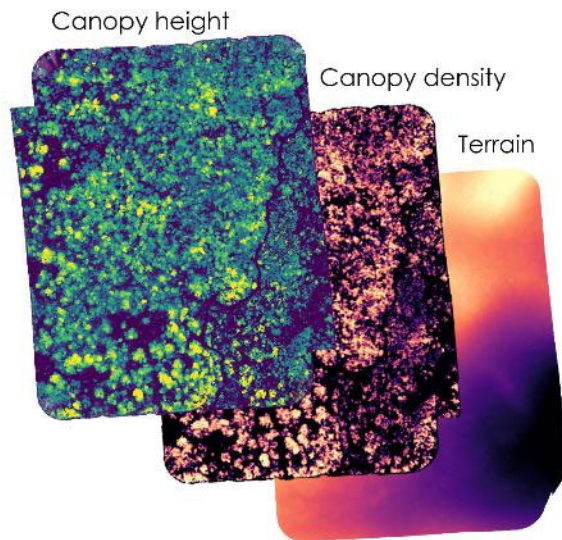
Return



Outputs



Outputs



Cloud Optimized GeoTiff (COG)
and Point-Clouds (COPC)



Collector & Environmental metadata

- Who?
- Sky code
- Wind speed
- Flight mission settings (via .kmz)



EMSA
Ecological Monitoring System Australia



SpatioTemporal
Asset Catalogs



Naturescan Explorer

Beta

Remote Sensing and AI-Powered Drone Solutions for
Advanced Biodiversity Monitoring



Select a collection below

- [NTAFIN](#)
- [TCNSTCH](#)
- [SANSSTP](#)
- [SAAGAW](#)

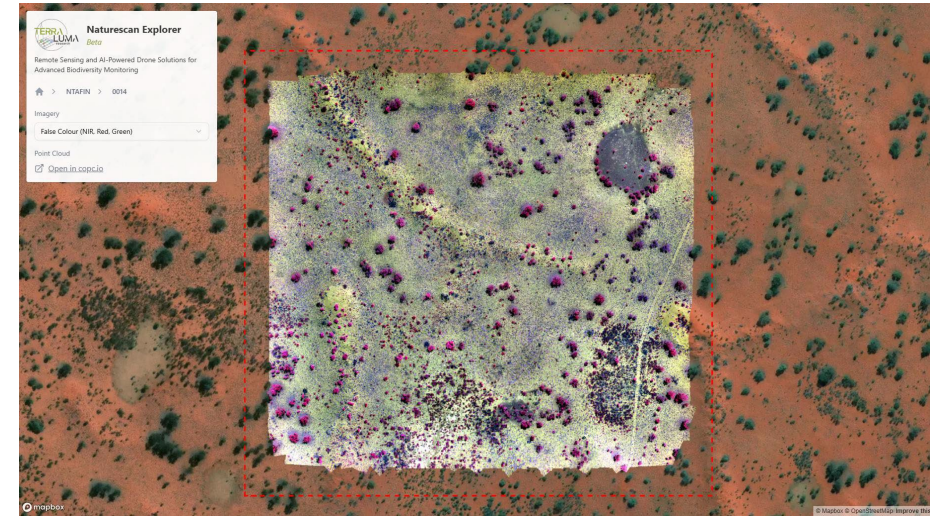


Four types of producers & users

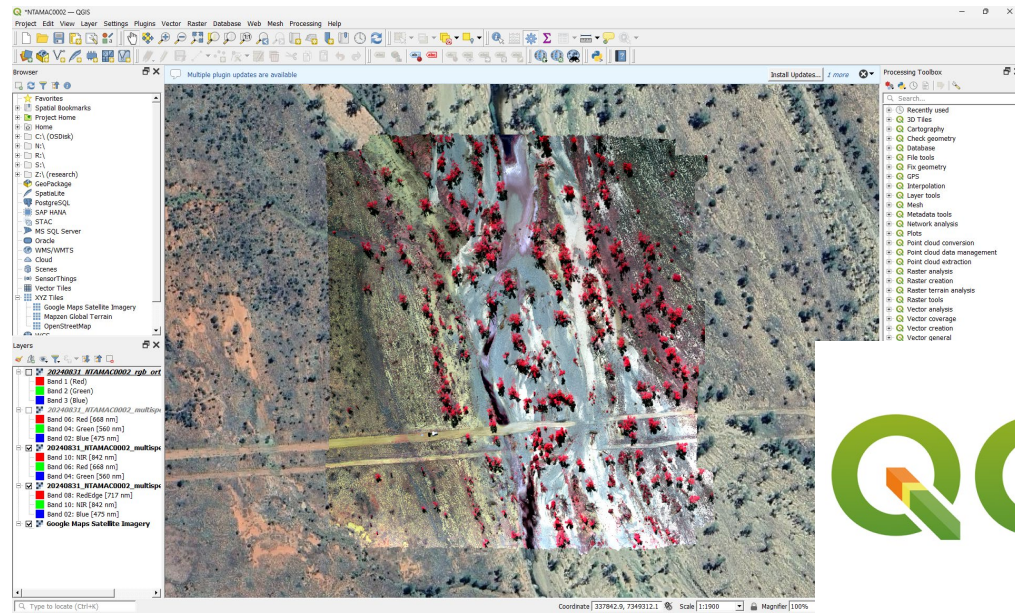
1. Data collector



2. Web viewer



3. GIS user



4. Data analytics – workflow developer





NatureScan

Remote Sensing and AI-Powered Drone Solutions for Advanced Biodiversity Monitoring

Professor Arko Lucieer (UTAS), Associate Professor Ben Sparrow (UoA), Alice Robbins (UTAS), Chris Callaghan (UoA), Ryan Haynes (UTAS) James Gregory (UTAS)

Phase1: hardware & protocols



DJI Mavic3M RTK
Low-cost high-accuracy user-friendly drone equipment
10 – 50 ha at 1 – 5 cm spatial resolution



TERN protocols for collection and processing adapted to new hardware and specific needs of the NatureScan project

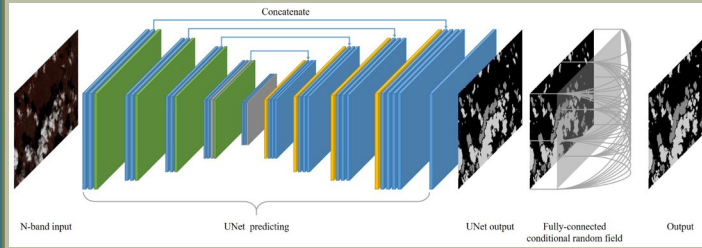


Establishment of data upload and processing workflows to produce analysis-ready datasets

- RGB orthomosaic
- Multispectral orthomosaic
- 3D photogrammetric point cloud



Phase2: EBV extraction with AI



Four ecological scales defined:

1. Sub-individual
2. Individual
3. Sub-community
4. Community (1 hectare plot scale)

Structural Metrics:

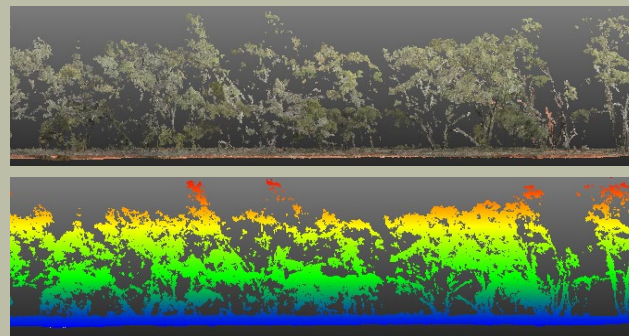
- Canopy height
- Canopy cover
- Vertical variability
- Growth form abundance
- Coarse woody debris

Compositional Metrics:

- Broad Taxonomic Group
- Structural variability
- Native vs non-native
- Spectral diversity

Functional Metrics:

- Vegetation indices
- Fractional Photosynthetic Cover



Phase3: Cal/Val & data collection



- Field observations for training of AI models, and validation of remote sensing products to inform biodiversity.
- Data collection across ecoregions and NVIS Major Vegetation Groups.
- Assess EBV models across a diverse range of ecosystems.
- Evaluate monitoring capability in context of Nature Repair requirements



Phase4: Accessibility, (Indigenous) Engagement & Training

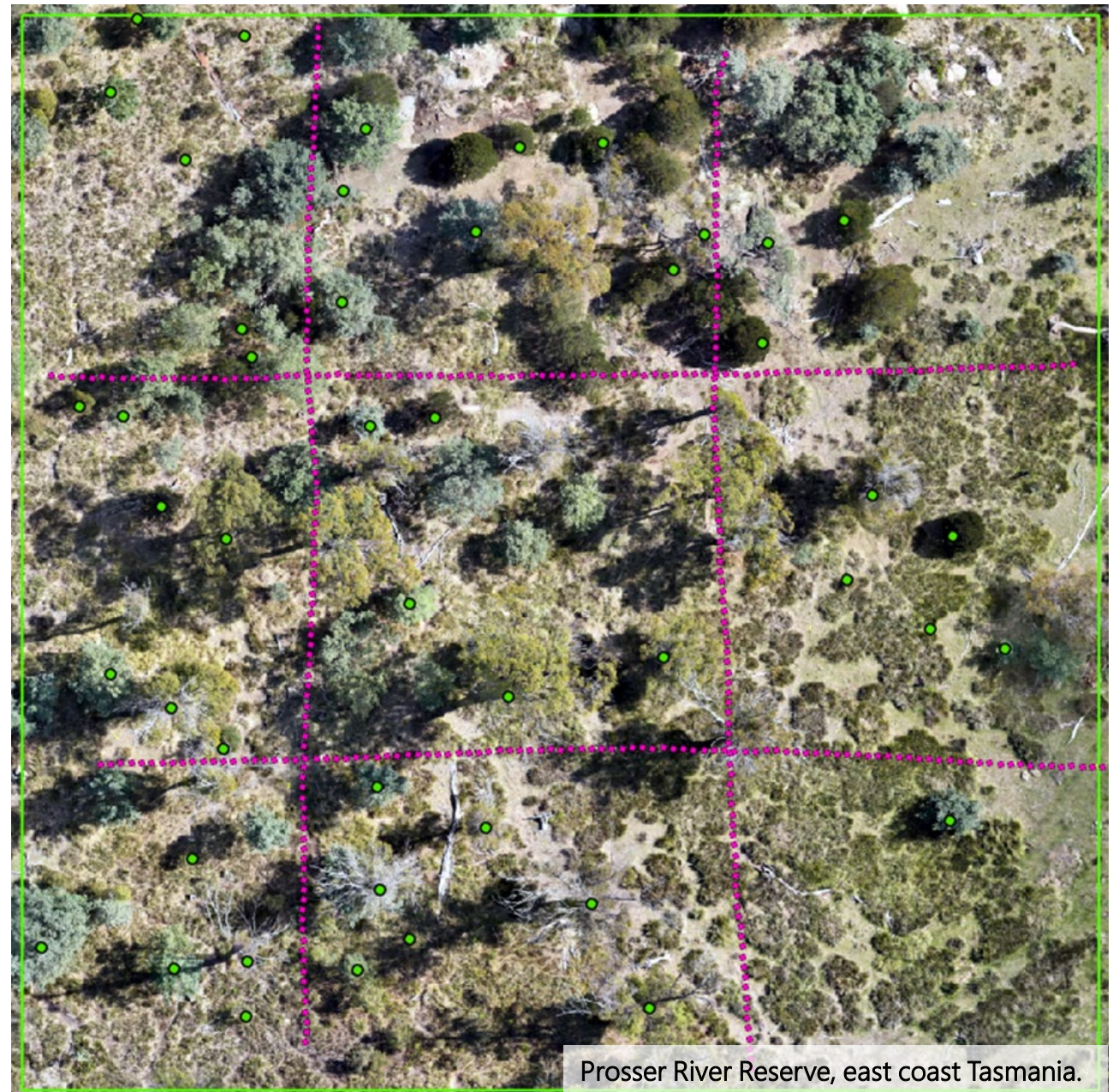


- Drone data collection protocol – published Oct 2025.
- Drone data processing protocol – will be available in early 2026.
- Partnerships with conservation organisations, private landholders and Traditional Owners.
- Engagement with Indigenous Australians through a knowledge sharing workshop
 - Evelyn Downs, 2026.
- Development of web based geospatial data interface for visualisation and analysis.



Remote sensing products to inform Essential Biodiversity Variables that can be supported and validated by field data.

Scale	Structural diversity	Compositional diversity	Functional diversity
Sub-individual	Coarse woody debris  Standing dead 	Leaf vs wood Photosynthetic vs non-photosynthetic	Ground cover (soil crust) 
Individual	Coarse woody debris  Growth form  Standing dead  Vegetation volume	Broad taxonomic groups  Native vs non-native 	Health  Recruitment and mortality  Vegetation indices
Sub-community	Canopy cover  Canopy height Coarse woody debris  Growth form abundance  Standing dead  Vegetation volume Vertical variability	Functional group variability Native vs non-native (relative abundance)  Population Density Spectral diversity Structural variability 	Canopy cover Fractional Photosynthetic cover  Native vs non-native (relative abundance)  Phenological change Vegetation indices
Community / Plot scale (1 ha) (vegetation type that is consistent and homogeneous)	Canopy cover  Canopy height Coarse woody debris  Growth form abundance  Vegetation volume Vertical variability	Fractional Vegetation Cover Functional group variability Population Density Spectral diversity Structural variability 	Canopy cover  Fractional Photosynthetic cover  Native vs non-native (relative abundance)  Phenological change Vegetation indices



Prosser River Reserve, east coast Tasmania.

Validation with Field Data

Future priorities and opportunities

- Translating drone data into meaningful ecosystem attributes
 - Composition
 - Structure
 - Function
 - Biodiversity
- Satellite calibration and validation
- Develop new satellite vegetation products (EBVs) from drone data and GeoAI
- Develop operational hyperspectral capability to map plant traits
- Explore new sensors and ensure consistency in data collection
- Explore future technology, e.g. robotics, to further improve linking of ground, air, and satellite scales